

# Prognostics and Health Management (PHM) for Rotating Systems

**Doug Goodman** 

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# Ridgetop Group, Inc.



Ridgetop Group Facilities in Tucson, AZ

- Worldwide nanotechnology R&D partners in industry and academia
- Foundation and focus in physics-of-failure for electronic systems
- Custom Engineering Services

- Arizona-based firm, founded in 2000, with focus on electronics for critical applications
- Advanced Diagnostics & Prognostics (ADP) and PHM/IVHM Expertise
- Technology leader in precision test structures for QA and prognostic applications
- Wide range of commercial and government customers



#### Ridgetop Europe Facilities in Brugge, Belgium

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#### **Partners and Customers**



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# Why Prognostics?

- Complex systems such as aircraft, radar systems, oil drilling equipment, etc., are being called upon to extend their useful service life
- "Black Swan" event mitigation.
- Statistical and model-based reliability methods fall short for critical systems
- Prognostics is key to enabling reliable operations of these systems in the future





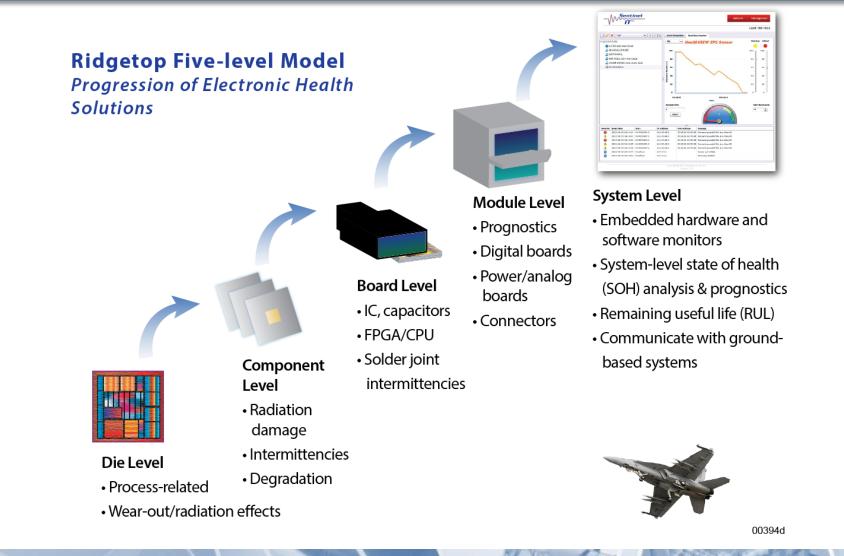


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## Reliability Issues in Complex System



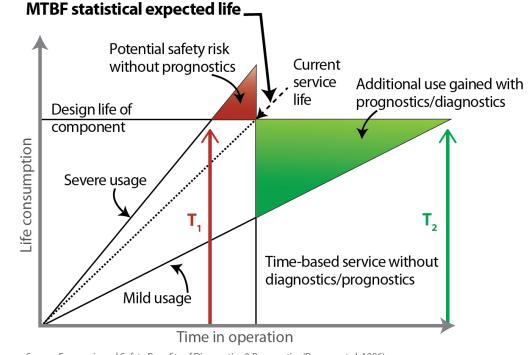
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#### Usage Environment

- Usage monitoring would provide a safety benefit if actual usage is more severe than predicted (see the red region, T<sub>1</sub>).
- Service life can be extended beyond normal replacement time if the actual usage severity is known (see the green region, T<sub>2</sub>).



Source: Economic and Safety Benefits of Diagnostics & Prognostics (Romero et al. 1996)

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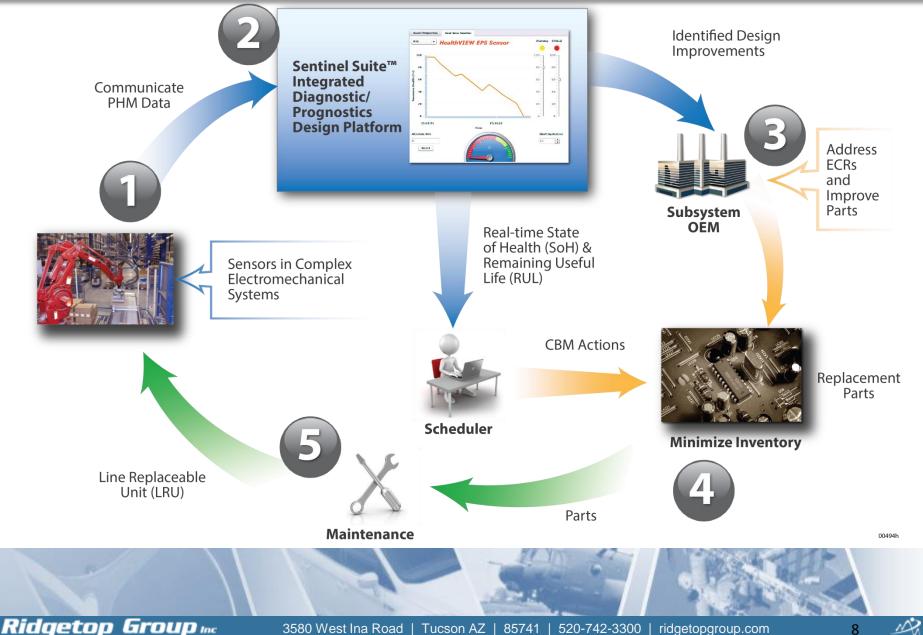
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PHM enables replacement only upon evidence of need

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# Prognostic Health Management (PHM) Ecosystem



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#### Building a Prognostic-Enabled System

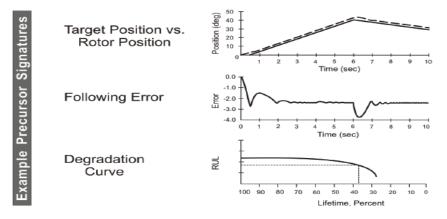
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#### **Basic Process Steps**

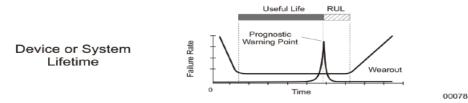
Step 1: Characterize Device or System Failures







Step 3: Calculate Remaining Useful Lifetime (RUL)



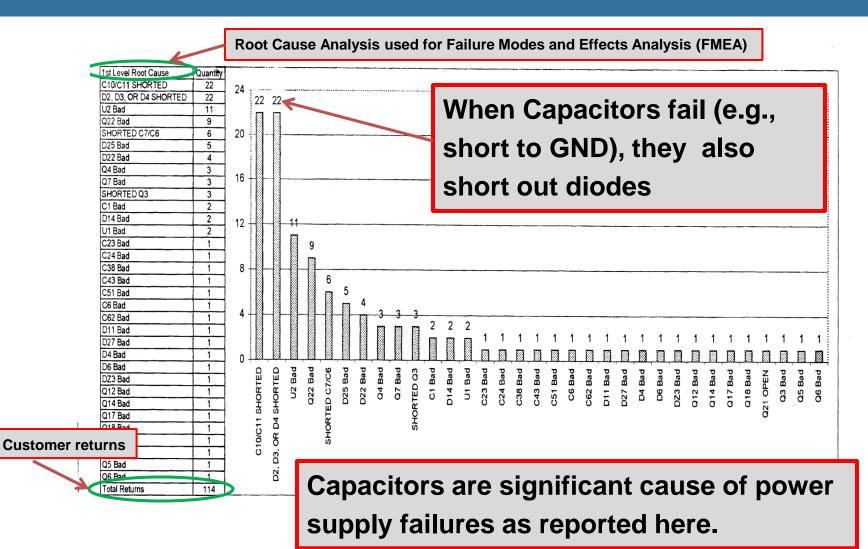
**Designing a Prognostic Solution** 

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## Pareto Analysis to Prioritize



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### **Implementation Elements**

- Advanced Sensing Methods
- Processing Platforms
- Anomaly Detection
- State of Health (SoH) Assessment
- Remaining Useful Life (RUL) Projection
- Linkages to other tools (Fault Management, Logistics Systems)



#### **Development Platforms**

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# PHM / Diagnostic Monitoring Scenarios

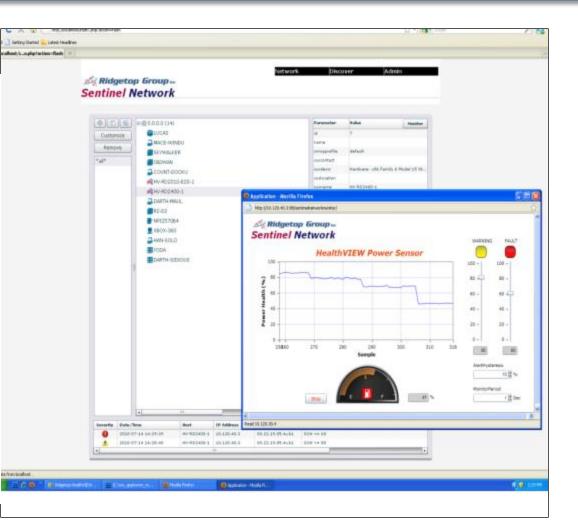
- Decisions are based on fault severity levels
  - On-Board for critical faults
  - Off-Board, single system or subsystem, for less critical faults
  - Mix of On- and Off-board, depending on fault severity
- Net-centric monitoring, off-board, multiple systems with geographic separation

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# Sentinel Motion<sup>™</sup> Platform

- Collection and analysis hub for prognostics
- Scalable, system level state of health (SoH) analysis & prognostics
- Automatic Sensor
   Network Discovery mode
- Anomaly detection
- Remaining useful life (RUL) algorithms



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# PHM for Rotating Systems

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## **Examples of Rotating Mechanisms**

- Helicopter Gear Boxes (pinion gear, planetary gears)
- Railroad Rolling Stock (wheels, axles)
- Electromechanical Actuators
- Industrial Equipment and Machine Tools
- Automotive Transmissions
- Wind Turbines

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# Special Problems with Rotating Systems

- Spinning shafts degrade with eccentricities from wear patterns
- Bearings that suspend spinning shafts can wear out
- Direct measurements are difficult to make due to rotation effects
- Slip rings are not always possible and they add noise
- Cabling is impractical and adds weight

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# Helicopter Gear Box Example

# Helicopters suspended as gearbox fault blamed for Super Puma ditching

#### STV 13 May 2012 12:02 BST

The owners of a helicopter which ditched in the North Sea last week grounded more aircraft today after an early investigation revealed a fault in its gearbox.

The move comes after an initial Air Accidents Investigation Branch examination of the EC225, which went down while carrying 12 passengers and two crew, showed it suffered a crack to a gearbox shaft.



Source: http://news.stv.tv/north/99554-helicopters-suspended-as-gearbox-fault-blamed-for-superpuma-ditching/

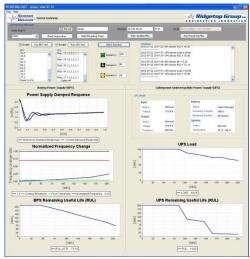
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# Helicopter Gear Box Health Monitoring

- Strategy is to place a self-contained sensor to monitor operating data of the pinion gear
- A separate sensor monitors a planetary gear for the helicopter transmission
- Sensor is a MEMS-based rotational vibration and speed sensor designed by Ridgetop
- Transmit vibration and speed data wirelessly using IEEE 802.15.4 to collection hub
- Analyze data stream for anomalies, and determine state of health (SoH) and remaining useful life (RUL)

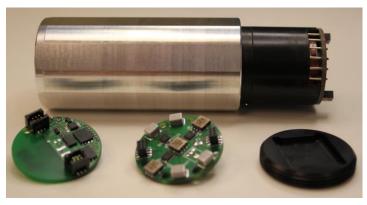




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# RotoSense<sup>™</sup> Module



- RotoSense is a wireless rotational vibration sensor
- IEEE 802.15.4 wireless implementation
- Sensing tool wear, chatter, or spindle balance in CNC applications
- Detecting prognostic vibrational signatures in rotating shafts or pinions to give early warning of gear tooth cracking or spalling in wind turbines and transmissions
- Applications include:
  - CNC
  - Down-hole oil & gas drilling
  - Wind turbines and transmissions

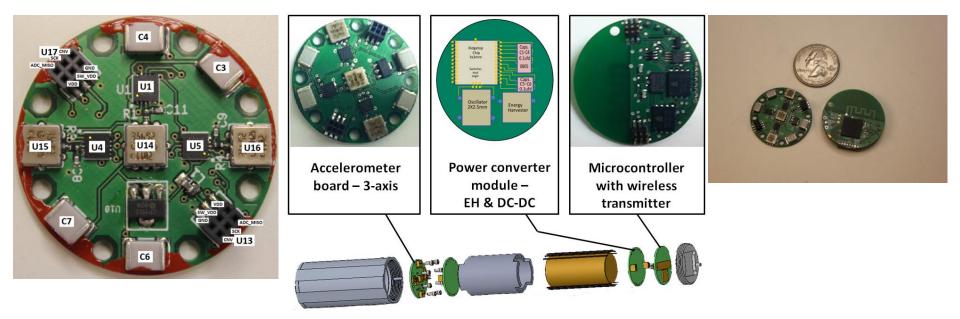
Specification	Value		
MEMS accelerometer peak impact	>200 g		
Operating temperature	93 °C		
Sensor housing	1.5" diameter x 3" length		
Sensor data memory	2 Mbits		
Accelerometer sensitivity	<20 mV/g at 100 Hz		
Wireless data rate	75 kbaud nominal		
Battery-powered	3.6 V high-temp battery, 4.5 Ah, 200 °C		
Battery life	4 months at a 50% duty cycle		
Sensor and signal conditioning bandwidth	20 kHz		
ADC resolution	16 bits		
ADC sample rate	>250 kHz		

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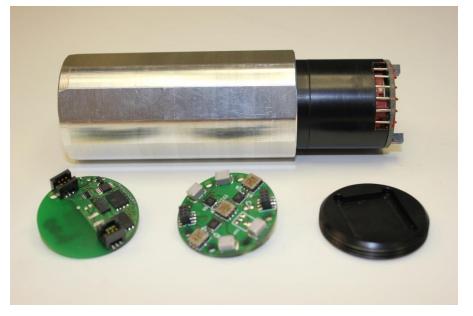
## **RotoSense Configuration**



# Small size allows the whole system to be mounted in the shaft of the transmission



#### RotoSense System





#### Complete module

# Module mounted in the shaft of the transmission



#### NASA Spinoff – RotoSense™



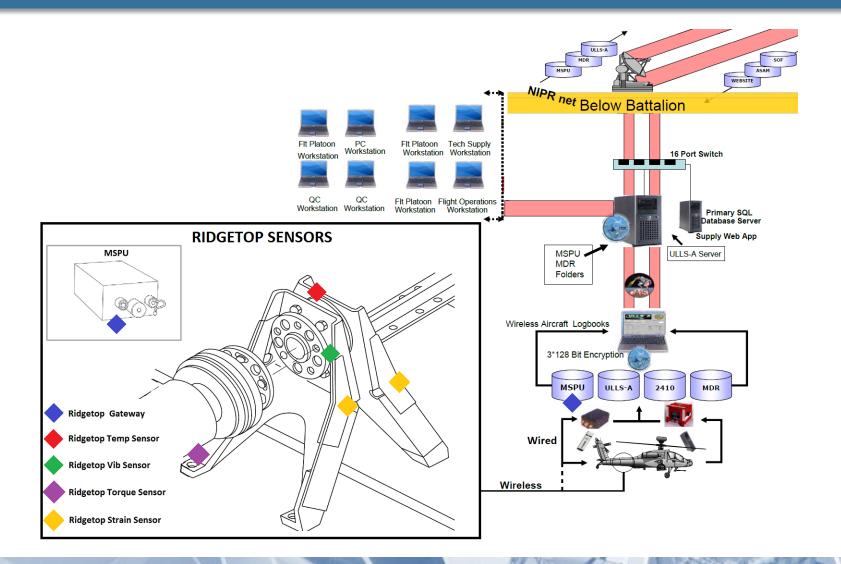
Full article here: http://spinoff.nasa.gov/Spinoff2012/t\_6.html

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#### Expanded Monitoring System



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### Wheel – Axle Applications

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#### **Problem Statement**

- Decaying railroad infrastructure: tracks, rolling stock, bridges
- Wheel cracks, defective bearings and connections to axles
- Transportation of dangerous materials such as flammable liquids and gases





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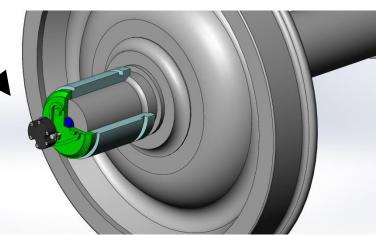


#### RotoSense<sup>™</sup> Wireless Rotational Vibration Sensor





Mount two wireless RotoSense™ sensors, one on each side of the axle end caps.



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# Wireless Testing Conducted at Railroad Test Facility



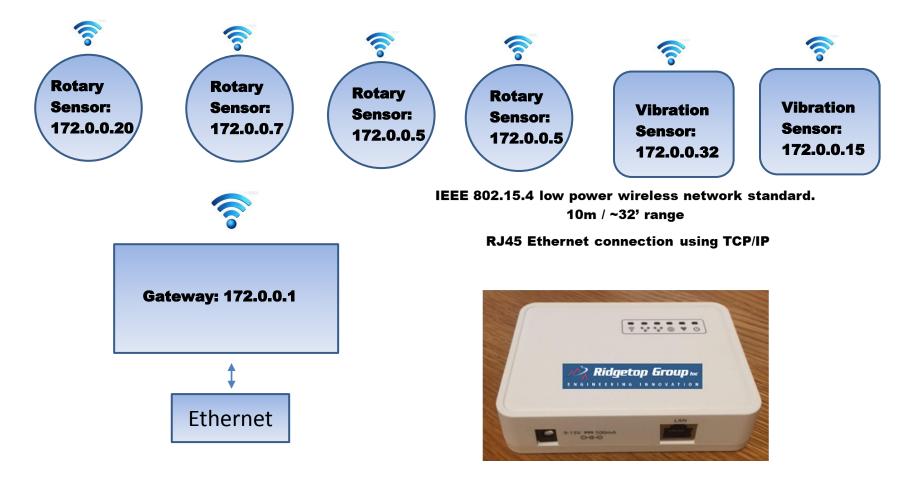




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#### Standard TCP/IP Implementation

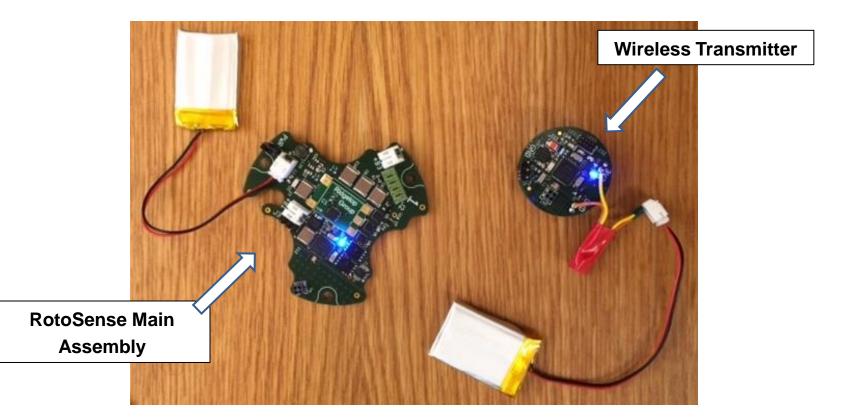
#### Each Gateway along with each sensor node has discoverable IP addresses



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#### RotoSense Hardware Components

#### **IEEE 802.15.4 low power wireless network standard**



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#### **Ridgetop's IoT Sensor Enablement Kit**

Flexible plugin board for additional sensors for IoT development with digital and analog sensors

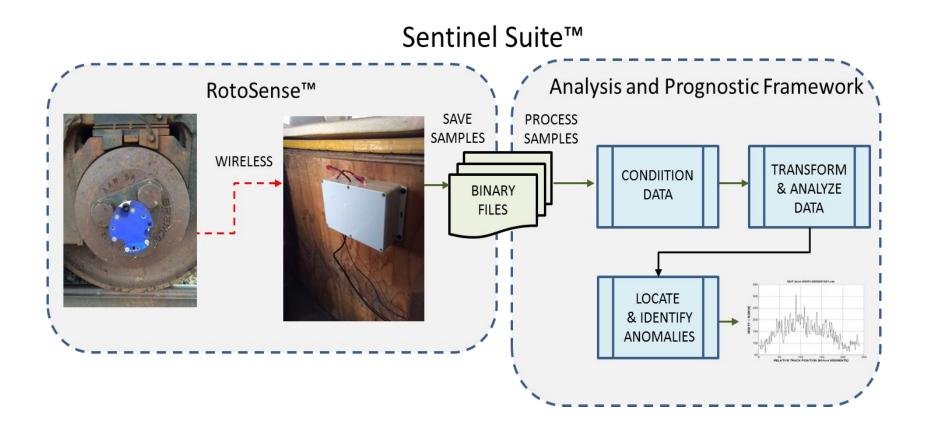
**Examples include: light level, temperature measurement,** strain/stress/pressure gauges, etc. along with I/O control







## **Railroad Car Application**





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#### Wireless Real Time Data Transfer



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Reply from 172.17.128.4: bytes-32 time-17ms TTL-254 Reply from 172.17.128.4: bytes-32 time-16ms TTL-254	gboul Settings	-device_v4.3etg	File Folder 3/(23)/2005 4:26 FM File Folder 3/(3)/2005 3:39 FM	
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Pinging 172.17.128.4 with 32 bytes of data:	Constitution file	1,024 KB	File 3/24/2015 8:05 AM	
Reply from 172.17.128.41 hytes-72 time:The TTL-254 Reply from 172.17.128.41 hytes-72 time:The TTL-254 Reply from 172.17.128.41 hytes-72 time:22nc TTL-254 Reply from 172.17.128.41 hytes-72 time:T6a TTL-254	Other Places 2	2		
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slow_32770_00		3/23/2015 10	:32 AM File	2 KB
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slow 32770 00	00000006	3/23/2015 10	:32 AM File	2 KB
slow_32770_00	00000007	3/23/2015 10	:32 AM File	2 KB
slow_32770_00		3/23/2015 10	:32 AM File	2 KB
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#### Gateway Data Transfer

Trivial File Transfer Protocol (TFTP) is embedded for reliable multi-node data exchanges with the gateway and sensors

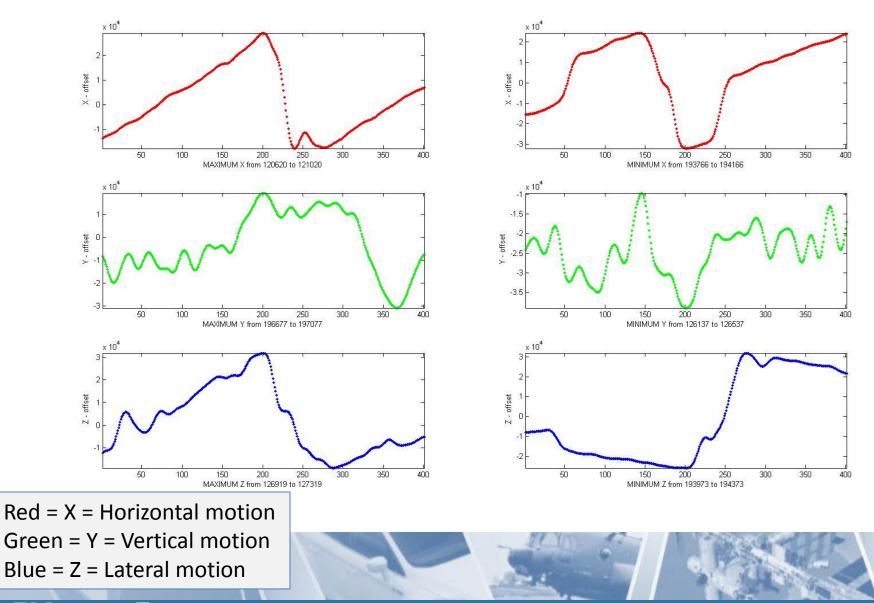
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Ping statistics for 172.17.128.4: Packets: Sent = 4, Received = 2, Lost = 2 (50% loss), Approximate round trip times in milli-seconds: Minimum = 13ms, Maximum = 17ms, Average = 15ms	Local File paceVools/Utpd32.450/sens Remote File /sens/tast Block Default •			
C:\Documents and Settings\XPMUser>ping 172.17.128.4	Size Default	iders 🔛 •		
Pinging 172.17.128.4 with 32 bytes of data:	Get But Bleak			× 🔿
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#### **Raw Data Plots**



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# Sensor Data

Two types of captured data files can be produced. Slow fixed rate streaming and fast variable length are supported. Multiple gateways and sensor nodes can produce these concurrently.

Name	Date modified	Туре	Size
slow_32770_000000000	3/23/2015 10:31 AM	File	1 KB
slow_32770_000000001	3/23/2015 10:31 AM	File	2 KB
slow_32770_000000002	3/23/2015 10:31 AM	File	2 KB
slow_32770_000000003	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000004	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000005	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000006	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000007	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000008	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000009	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000010	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000011	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000012	3/23/2015 10:32 AM	File	2 KB
slow_32770_000000013	3/23/2015 10:32 AM	File	2 KB
Name	Date modified	Туре	Size
fast_32771_000000000	3/23/2015 4:22 PM	File	1,024 KB
fast_32771_000000001	3/24/2015 8:05 AM	File	1,024 KB

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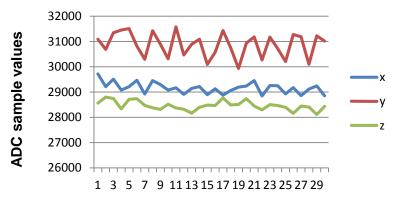
### Sensor Data File Format

The data file format is raw 16bit ADC samples arranged as X, Y & Z values of the supported mems sensor type integrated with these sensor devices.

The format header allows the data files to have system independence after collection and distribution for post processing analysis and visualization. This arrangement coupled with various types of sensor hardware provides an extensible sensor network system approach.

#### Sample output of the data shown exported to a CSV file and plotted in MS Excel

х	у	z
29719	31089	28561
29208	30687	28799
29506	31340	28742
29078	31450	28330
29210	31506	28711
29467	30811	28736
28918	30290	28474
29451	31423	28377
29296	30885	28314
29079	30313	28516
29166	31574	28369



ADC sample numbers

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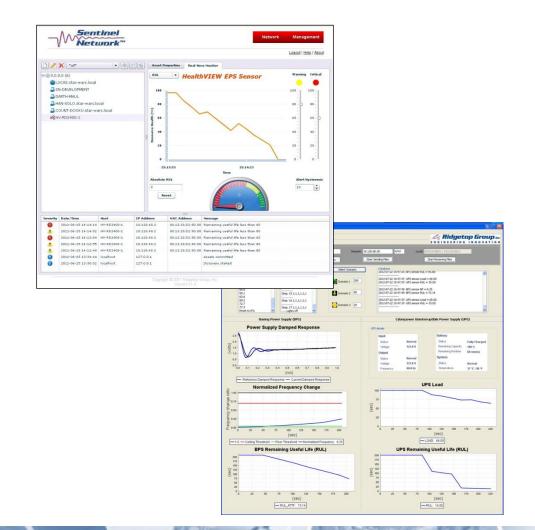
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39

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# RailSafe<sup>™</sup> Integrity Analysis Platform

- Continuous sensor monitoring with analysis using proven PHM algorithms
- Provides system-level State of Health (SoH) indication with accurate Remaining Useful Life (RUL) estimates
- Results can be integrated with existing CBM systems

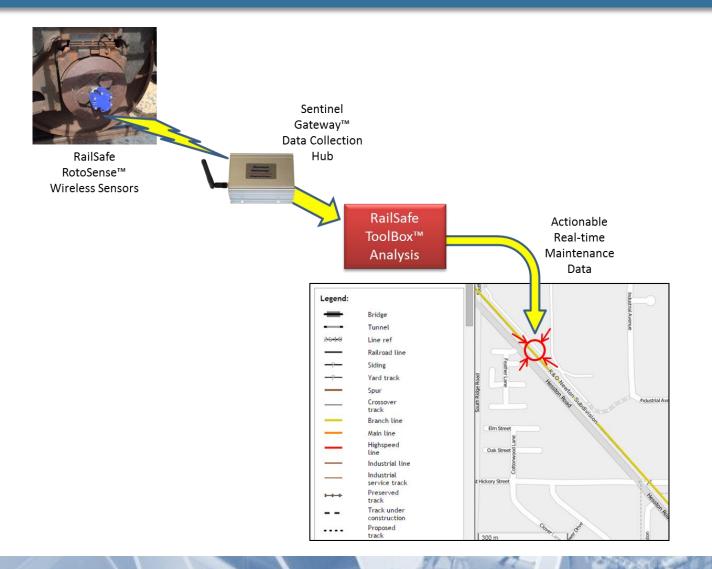


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# RailSafe<sup>™</sup> Complete Solution



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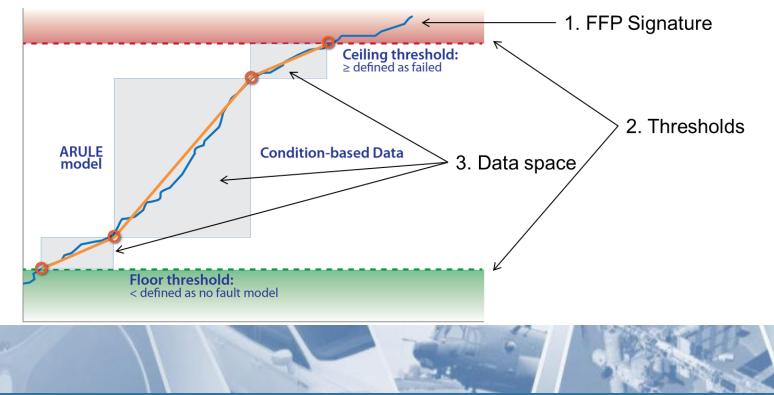
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# Algorithm Development

# Fault to Failure Progression Model

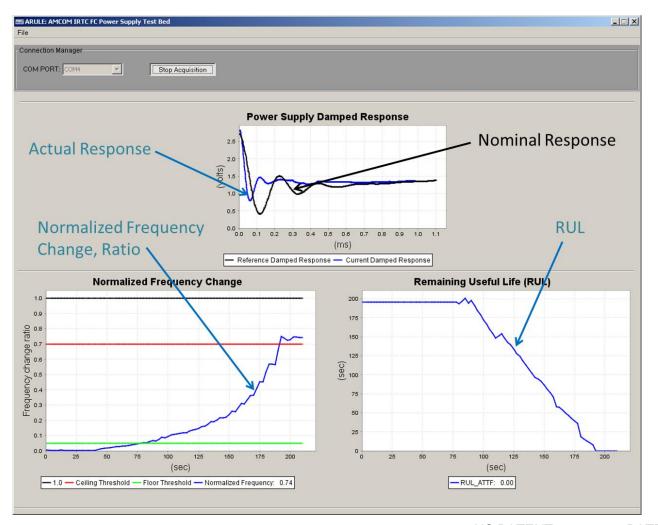
- Ridgetop developed software that takes advantage of the fact that failure modes produce predictable degradation signatures.
- Each input data sample is used to adapt an Fault to Failure Progression (FFP) signature definition to the data.
- The adapted FFP signature definition is then used to produce accurate RUL and SoH estimates that can be used to generate diagnostic and prognostic information: messages, plots, thermometers and so on.



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# ARULE Algorithm Example



US PATENT 7,619,908; PATENT PENDING

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# **EMA Actuator Prognostics**

# Actuator Hardware Configuration



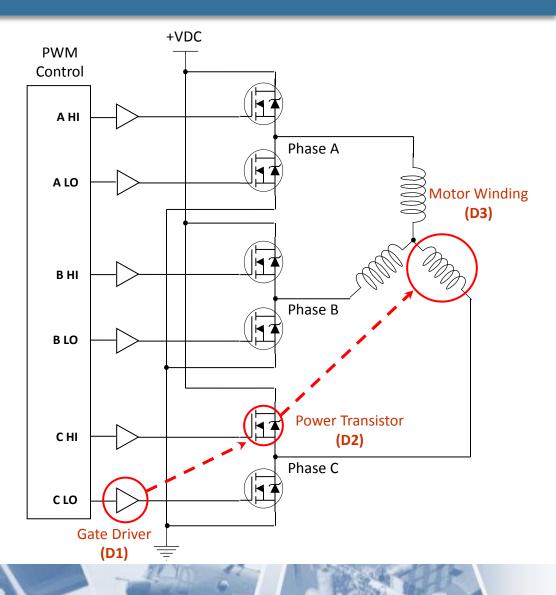
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# **Actuator Power Drive Prognostics**

- Typical Problem: Gate drive (D1) fault with progression to the power transistors (D2) and motor windings (D3) of each phase
- Acquire and characterize the pertinent multivariate servo drive data associated with each fault condition (both electrical and mechanical) and the resulting stress effect on other components in the system
- Develop the fault-to-failure progression (FFP) signatures of the acquired multivariate data to populate fault dictionary
- Results: Detection of precursor events that mark impending failure of the servo drive subsystem or damage to its individual components



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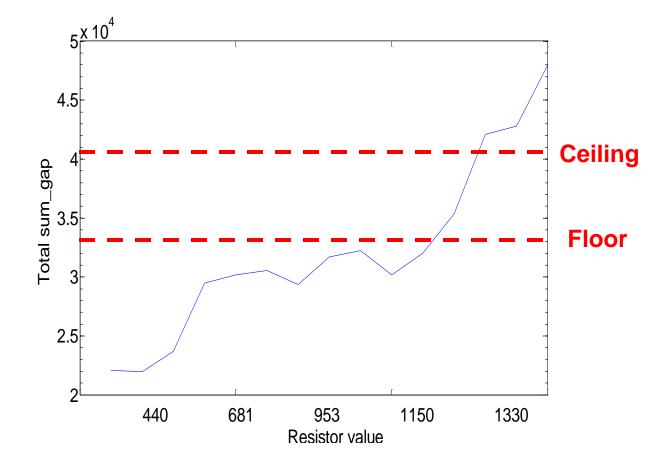
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# Analysis

- The goal of our data analysis methodology is to create a signature that can be used to compute the level of degradation of any future test runs of a motion profile
- Data collected with a threshold level is used to define 'healthy' data
- This methodology computes differences from the golden signature and sums the differences over time
- The summed differences relate to fault degradation
- The fault degradation is used to determine a fault to failure progression



# Fault to Failure Progression (FFP) Signature



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# **Actuator Results**

- Defined EMA Actuator Health Management System
- Identified additional observation points for prognostics of the electronic unit (EU) of an EHA
- Provided SoH and RUL for complex system

# Fault Dictionary Development

### **Prognostic / Diagnostic Fault Dictionary**

Time	Fault Ref	Location		Description
16:21:02	E213_006	EHA Drive Card		MOSFET Degraded
16:43:02	M166_001	Gear Box A		Broken Tooth
16:45:02	M166_002	Gear Box A		Gear Spalling
17:04:02	H006_001	EHA Hydraulic Valve		Pressure drop
EHA VALVE		<ol> <li>EHA Hydraulic Valve Test</li> <li>Apply test sequence Q_12_DS2</li> <li>Monitor input drive current at test point 13</li> <li>Verify excessive current.</li> <li>Replace part and retest.</li> </ol>		

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# Conclusion

- Rotating / moving systems pose a difficult challenge for monitoring, diagnosis, and prognosis
  - Wear out and degradation effects are difficult to observe, especially for internal components
  - They can be subject to a very wide range of environmental conditions
  - Sensor data is often very noisy
  - Statistical and model-based predictive analytical methods often fall short
- Ridgetop's Sentinel Suite
  - Sensors
    - Designed to be close or inside the monitored component for optimal sensitivity
    - $\rightarrow$  Designed to withstand harsh environments
  - Advanced diagnostic and prognostic software
    - $\rightarrow$  Effectively extract the signal from the noise
    - $\rightarrow$  Efficiently compute key diagnostic and prognostic metrics, e.g., SoH, RUL

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# **Questions?**

 Slides and recording of the webinar will be available shortly via an e-mail from Ridgetop

- E-mail follow-up questions & comments to Doug Goodman at <u>dgoodman@ridgetopgroup.com</u>
- Please fill out our brief feedback survey at: <u>https://www.surveymonkey.com/r/57NDFVP</u>

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# **Questions?**

# Thank you!

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